

- **DO NOT open the exam booklet until you are told to begin. You should write your name at the top and read the instructions.**
- Organize your work, in a reasonably neat and coherent way, in the space provided. If you wish for something to not be graded, please strike it out neatly. I will grade only work on the exam paper, unless you clearly indicate your desire for me to grade work on additional pages.
- You may use any results from class or the text, but you must cite the result you are using. You must prove everything else.
- This exam contains 5 numbered problems. The last page is blank. Check to see if any pages are missing. Point values are in parentheses.
- **No books, notes, or electronic devices are allowed.**

Problem	Points	Score
1	30	
2	15	
3	20	
4	15	
5	20	
Total:	100	

Definition 1. A vector space is a set V equipped with two operations:

1. *Addition:* adding any pair of vectors $\mathbf{v}, \mathbf{w} \in V$ produces another vector $\mathbf{v} + \mathbf{w} \in V$;
 2. *Scalar Multiplication:* multiplying a vector $\mathbf{v} \in V$ by a scalar $c \in \mathbb{R}$ produces a vector $c\mathbf{v} \in V$.
These are subject to the following axioms, valid for all $\mathbf{u}, \mathbf{v}, \mathbf{w} \in V$ and all scalars $c, d \in \mathbb{R}$:
- *Commutativity of Addition:* $\mathbf{v} + \mathbf{w} = \mathbf{w} + \mathbf{v}$.
 - *Associativity of Addition:* $\mathbf{u} + (\mathbf{v} + \mathbf{w}) = (\mathbf{u} + \mathbf{v}) + \mathbf{w}$.
 - *Additive Identity:* There is a zero element $\mathbf{0} \in V$ satisfying $\mathbf{v} + \mathbf{0} = \mathbf{v} = \mathbf{0} + \mathbf{v}$.
 - *Additive Inverse:* For each $\mathbf{v} \in V$ there is an element $-\mathbf{v} \in V$ such that $\mathbf{v} + (-\mathbf{v}) = \mathbf{0} = (-\mathbf{v}) + \mathbf{v}$.
 - *Distributivity:* $(c + d)\mathbf{v} = (c\mathbf{v}) + (d\mathbf{v})$, and $c(\mathbf{v} + \mathbf{w}) = (c\mathbf{v}) + (c\mathbf{w})$.
 - *Associativity of Scalar Multiplication:* $c(d\mathbf{v}) = (cd)\mathbf{v}$.
 - *Unit for Scalar Multiplication:* the scalar $1 \in \mathbb{R}$ satisfies $1\mathbf{v} = \mathbf{v}$.

1. Consider the following system of linear equations

$$\begin{aligned} x + 2y + 2z - 2u &= a, \\ 3x + 7y + z + 4u &= b, \\ -x - 3y + 4z + 3u &= c \end{aligned}$$

(a) (20 points) For which values of a , b and c the system above has no solution, one solution, infinitely many solutions

We start with the augmented matrix:

$$\left(\begin{array}{cccc|c} 1 & 2 & 2 & -2 & a \\ 3 & 7 & 1 & 4 & b \\ -1 & -3 & 4 & 3 & c \end{array} \right) \xrightarrow[R3+R1]{R2-3R1} \left(\begin{array}{cccc|c} 1 & 2 & 2 & -2 & a \\ 0 & 1 & -5 & 10 & b-3a \\ 0 & -1 & 6 & 1 & c+a \end{array} \right) \xrightarrow{R3+R2} \left(\begin{array}{cccc|c} 1 & 2 & 2 & -2 & a \\ 0 & 1 & -5 & 10 & b-3a \\ 0 & 0 & 1 & 11 & c+b-2a \end{array} \right)$$

As we can see, all three pivots are nonzero. Since there are

3 equations and the rank of the matrix is 3, for any choice of a , b and c the system always

has infinitely many solutions.

(b) (10 points) Find the solution of the above system for

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}.$$

Let's plug in the values of a, b and c in the augmented matrix.

$$\left(\begin{array}{cccc|c} 1 & 2 & 2 & -2 & 3 \\ 0 & 1 & -5 & 10 & -8 \\ 0 & 0 & 1 & 11 & -4 \end{array} \right).$$

Thus, $z + 11u = -4$, if we let $u = t$ be the free variable, we get $z = -11t - 4$.

$$y - 5z + 10u = -8 \quad y - 5(-11t - 4) + 10t = -8, \quad y = -65t - 28.$$

$$\text{Finally, } x + 2y + 2z - 2u = 3 \quad x + 2(-65t - 28) + 2(-11t - 4) - 2t = 3$$

$$x = 154t + 67.$$

$$\text{The solution would be } \begin{pmatrix} x \\ y \\ z \\ u \end{pmatrix} = \begin{pmatrix} 154t + 67 \\ -65t - 28 \\ -11t - 4 \\ t \end{pmatrix}.$$

2. By using the following fact: $\det(\mathbf{AB}) = \det(\mathbf{A}) \det(\mathbf{B})$, prove the following propositions

(a) (5 points) Prove that $\det(\mathbf{A}^{-1}) = \frac{1}{\det(\mathbf{A})}$

We use the fact that $\mathbf{I} = \mathbf{A} \cdot \mathbf{A}^{-1}$. Thus,

$$\det(\mathbf{I}) = \det(\mathbf{A} \cdot \mathbf{A}^{-1}) = \det(\mathbf{A}) \cdot \det(\mathbf{A}^{-1}).$$

To conclude the proof, it is enough to note, that $\det(\mathbf{I}) = 1$, which implies that

$$\det(\mathbf{A}^{-1}) = \frac{1}{\det(\mathbf{A})}.$$

(b) (5 points) Prove that $\det(\mathbf{AB}) = \det(\mathbf{BA})$.

$$\begin{aligned} \det(\mathbf{AB}) &= \det(\mathbf{A}) \cdot \det(\mathbf{B}) = \\ &= \det(\mathbf{B}) \cdot \det(\mathbf{A}) = \det(\mathbf{BA}). \end{aligned}$$

(c) (5 points) Prove that $\det(\mathbf{AB}^{-1}) = \frac{\det(\mathbf{A})}{\det(\mathbf{B})}$.

$$\begin{aligned} \det(\mathbf{AB}^{-1}) &= \det(\mathbf{A}) \cdot \det(\mathbf{B}^{-1}) = \\ &= \det(\mathbf{A}) \cdot \frac{1}{\det(\mathbf{B})} = \frac{\det(\mathbf{A})}{\det(\mathbf{B})}. \end{aligned}$$

3. Given the following vectors

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 2 \\ 4 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 2 \\ 0 \\ 1 \\ 5 \end{bmatrix}, \mathbf{v}_3 = \begin{bmatrix} 0 \\ 1 \\ 3 \\ 5 \end{bmatrix}.$$

(a) (10 points) Check whether $\mathbf{v}_1$, $\mathbf{v}_2$ and $\mathbf{v}_3$ are independent or no.

To check independence it is enough to find the rank of the following matrix

$$\begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 2 & 1 & 3 \\ 4 & 5 & 5 \end{bmatrix} \xrightarrow{\substack{R_3 - 2R_1 \\ R_4 - 4R_1}} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 0 & -3 & 3 \\ 0 & -3 & 5 \end{bmatrix} \xrightarrow{R_2 \leftrightarrow R_3} \begin{bmatrix} 1 & 2 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 1 \\ 0 & -3 & 5 \end{bmatrix} \xrightarrow{R_1 - 3R_2} \begin{bmatrix} 1 & 2 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 2 \end{bmatrix} \xrightarrow{R_4 - 2R_3}$$

$$\xrightarrow{R_4 - 2R_3} \begin{bmatrix} 1 & 2 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

As we can see the rank is 3.
Thus, the vectors are linearly independent.

(b) (10 points) What is the span of $\mathbf{v}_1$, $\mathbf{v}_2$ and $\mathbf{v}_3$? Is it equal to $\mathbb{R}^4$? Justify your answer.

Since $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ are independent, their span would be a 3-dimensional subspace of $\mathbb{R}^4$.

No, 3 vectors can not span $\mathbb{R}^4$

4. (15 points) Determine whether the following set of vectors is a basis of $\mathbb{R}^3$ or no.

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 5 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}, \mathbf{v}_3 = \begin{bmatrix} 0 \\ 1 \\ 5 \end{bmatrix}.$$

We need to check 2 things: linear independence and that $\text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\} = \mathbb{R}^3$.

Since there are exactly 3 vectors, it is enough to calculate the rank of $[\mathbf{v}_1 \ \mathbf{v}_2 \ \mathbf{v}_3]$ if it is 3, then $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ would be a basis.

$$\begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 1 \\ 5 & 0 & 5 \end{bmatrix} \xrightarrow{R_3 - 5R_1} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 1 \\ 0 & -10 & 5 \end{bmatrix} \xrightarrow{R_3 + 10R_2} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 15 \end{bmatrix}$$

Thus, $\text{rank}([\mathbf{v}_1 \ \mathbf{v}_2 \ \mathbf{v}_3]) = 3$.

Yes, $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ form a basis of $\mathbb{R}^3$.

5. (20 points) A planar vector field is a function that assigns a vector

$$\mathbf{v}(x, y) = \begin{bmatrix} v_1(x, y) \\ v_2(x, y) \end{bmatrix}$$

to each point $(x, y) \in \mathbb{R}^2$. Prove that the set of all planar vector fields forms a vector space (the definition of the vector space is on the front page).

Let's denote the set of all planar vector fields by V .

We define summation and scalar multiplication on V as follows.

$$u, v \in V \quad \begin{aligned} (u+v)(x, y) &= u(x, y) + v(x, y) = \begin{bmatrix} u_1(x, y) + v_1(x, y) \\ u_2(x, y) + v_2(x, y) \end{bmatrix} \quad \text{for all } (x, y) \in \mathbb{R}^2 \end{aligned}$$

$$c \in \mathbb{R} \quad (cV)(x, y) = c \cdot V(x, y) = \begin{bmatrix} c v_1(x, y) \\ c v_2(x, y) \end{bmatrix} \quad \text{for all } (x, y) \in \mathbb{R}^2.$$

Now, we have to verify the 7 axioms.

① Commutativity of addition:

For all $u, v \in V$ $u + v = v + u$.

$$\begin{aligned} \text{for all } (x, y) \in \mathbb{R}^2 \quad u(x, y) + v(x, y) &= \begin{bmatrix} u_1(x, y) + v_1(x, y) \\ u_2(x, y) + v_2(x, y) \end{bmatrix} = \begin{bmatrix} v_1(x, y) + u_1(x, y) \\ v_2(x, y) + u_2(x, y) \end{bmatrix} \\ &= v(x, y) + u(x, y). \quad \text{Thus, } u + v = v + u. \end{aligned}$$

② Associativity of addition

For all $u, v, w \in V$ $u + (v + w) = (u + v) + w$

$$\begin{aligned} \text{For all } (x, y) \in \mathbb{R}^2 \quad u(x, y) + (v(x, y) + w(x, y)) &= \begin{bmatrix} u_1(x, y) + (v_1(x, y) + w_1(x, y)) \\ u_2(x, y) + (v_2(x, y) + w_2(x, y)) \end{bmatrix} \\ &= \begin{bmatrix} (u_1(x, y) + v_1(x, y)) + w_1(x, y) \\ (u_2(x, y) + v_2(x, y)) + w_2(x, y) \end{bmatrix} = (u(x, y) + v(x, y)) + w(x, y). \end{aligned}$$

(3) Additive Identity:

for all $(x, y) \in \mathbb{R}^2$ $0(x, y) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ $u(x, y) + 0(x, y) = \begin{bmatrix} u_1(x, y) + 0 \\ u_2(x, y) + 0 \end{bmatrix} = \begin{bmatrix} u_1(x, y) \\ u_2(x, y) \end{bmatrix} = u(x, y)$. Similarly, for $0(x, y) + u(x, y)$.

(4) Additive Inverse:

For any $u \in V$ define $-u \in V$ as

$-u(x, y) = \begin{bmatrix} -u_1(x, y) \\ -u_2(x, y) \end{bmatrix}$ $u(x, y) + (-u)(x, y) = \begin{bmatrix} u_1(x, y) - u_1(x, y) \\ u_2(x, y) - u_2(x, y) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$. Similarly, for $(-u)(x, y) + u(x, y)$.

(5) Distributivity: $(c+d)v = cv + dv$

$((c+d)v)(x, y) = \begin{bmatrix} (c+d)v_1(x, y) \\ (c+d)v_2(x, y) \end{bmatrix} = \begin{bmatrix} cv_1(x, y) \\ cv_2(x, y) \end{bmatrix} + \begin{bmatrix} dv_1(x, y) \\ dv_2(x, y) \end{bmatrix} = cv(x, y) + dv(x, y)$.

Similarly, for $c(u+v) = cu + cv$.

(6) Associativity for scalar multiplication: $c(d \cdot v) = (cd)v$

For all $(x, y) \in \mathbb{R}^2$, $(c(dv))(x, y) = \begin{bmatrix} c(dv_1(x, y)) \\ c(dv_2(x, y)) \end{bmatrix} = \begin{bmatrix} (cd)v_1(x, y) \\ (cd)v_2(x, y) \end{bmatrix} = ((cd)v)(x, y)$

(7) Unit for scalar multiplication $1 \cdot v = v$ for all $v \in V$.

$(1 \cdot v)(x, y) = \begin{bmatrix} 1 \cdot v_1(x, y) \\ 1 \cdot v_2(x, y) \end{bmatrix} = \begin{bmatrix} v_1(x, y) \\ v_2(x, y) \end{bmatrix} = v(x, y)$ for all $(x, y) \in \mathbb{R}^2$.